EE CprE SE 491 - MAY15-28 MicroCART Senior Design Team

Meeting Minutes - Week 14

December 9, 2014

Attendance:

Team Members: (All Present)
Paul Gerver
Tyler Kurtz
Joe Benedict
Jacob Rigdon
Matt Vitale
Ravi Nagaraju
Adam Campbell

Advisors: (All Present)
Dr. Phillip Jones
Dr. Nicola Elia

Agenda Items and Discussion

- 1) Advisor reviewed the Milestone Presentation power point
 - Overall format change to match ISU CprE template
 - Add a problem statement slide
 - Identify issue with having current gyroscope as a "black box"
 - Include reasons why we are using the FPGA board
 - Identify: "present state", "end result" and "problems"
 - Add graphics to data analysis slide
 - Include information on 3-axis testing platform
 - Include information on OmniCoor collaboration
 - Add information on manual override switch
 - Add information on operating environment
 - Add "agricultural research" to project scope
 - Add bullet points to GUI slide
- 2) PID controls
 - Sensor data mixing with RC signal on Zybo
 - Yaw feedback needs to be switched from camera system to onboard gyroscope
 - Yaw PID control will reference velocity
 - Yaw manual control from transmitter will be velocity
 - Roll and pitch PID controls will reference vehicle angle

3) Semester-end goals

 Concentrate all efforts on tuning the PID controls for manual flight demonstration for the client

Deliverables for next week

Joe

- Updated milestone presentation slides
- Attend Milestone Presentation
- Testing and troubleshooting PID controls for manual flight for client demo

Paul

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Matt

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Ravi

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